



# Belgisch **Wegen**congres Congrès belge de la **Route**

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## Use of Automotive Digital Twin for extended PMS

Kris De Meester  
XenomatiX





## Agenda:

- **Road Survey market today**
- **Automotive development opportunity**
- **Automotive LiDAR for road surveys**
- **Example - LiDAR road survey**
- **Example - road survey visualization**
- **XenomatiX info**
- **Take-aways**



## How is this done today



Manual inspection

- ✗ Labor-intensive
- ✗ Operator dependent
- ✗ Very partial data



Balanced wheel (APL)

- ✗ Waviness only
- ✗ Requires fixed speed
- ✗ Only wheel track

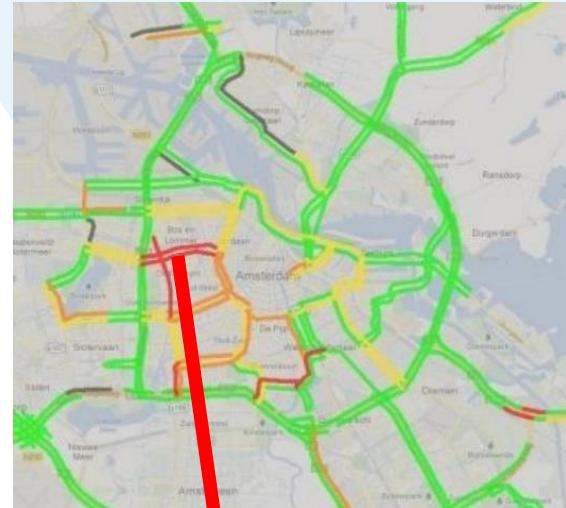
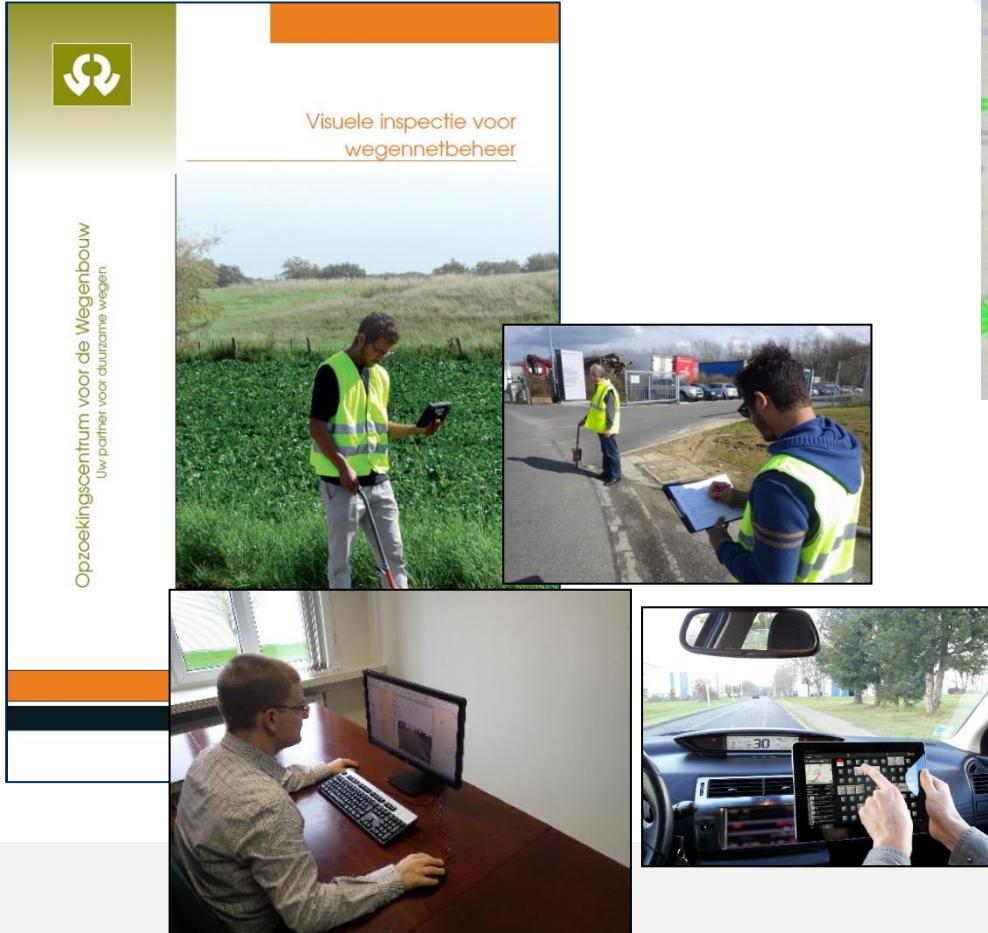


Multi-functional vehicles

- ✗ Very accurate & complete
- ✗ Expensive
- ✗ Road characteristics but no digital twin



# Visual Inspection for PMS



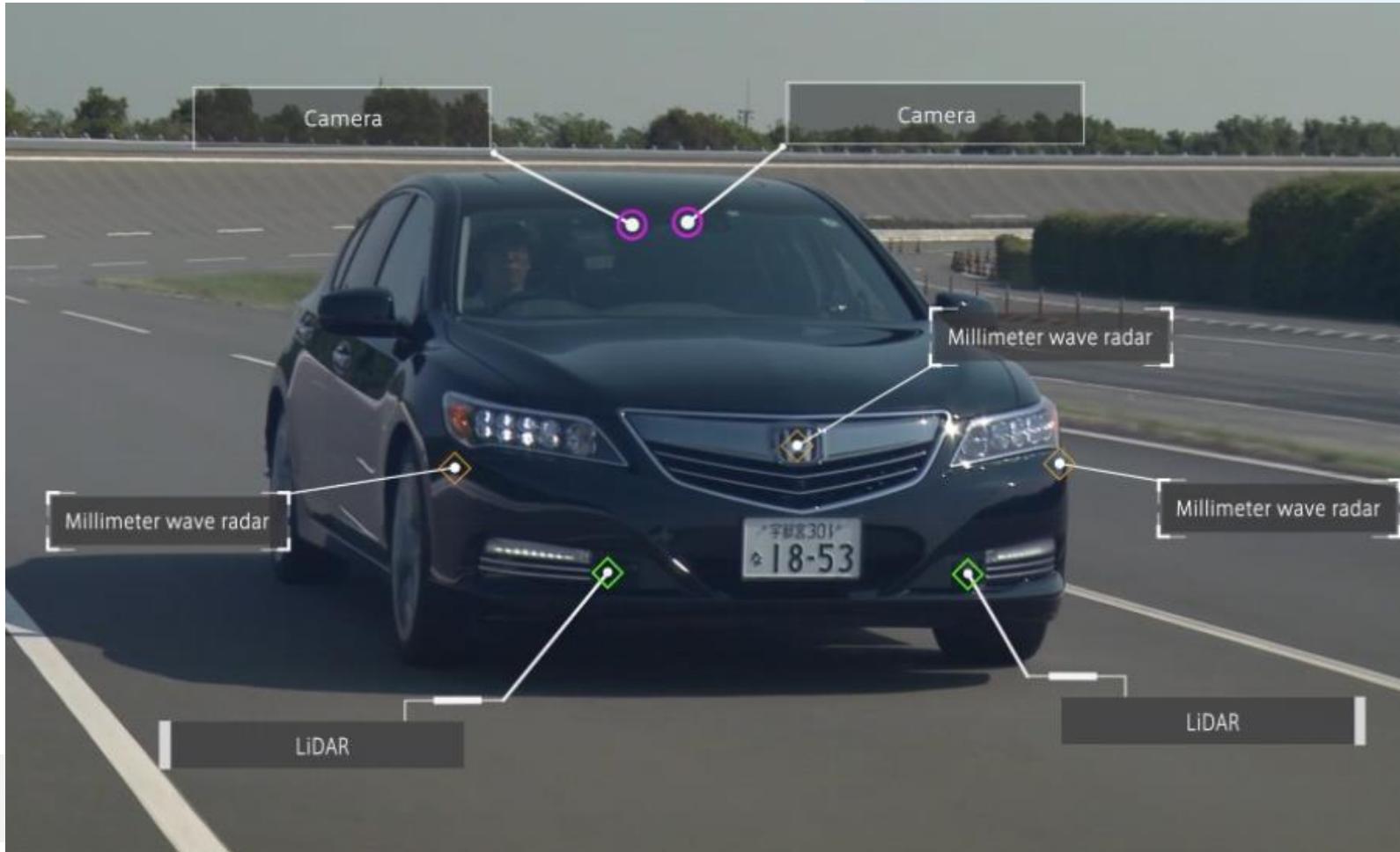


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# Autonomous vehicles





## The (near) future: DIGITAL TWIN

All roads will be digitized periodically and completely to:

- ✗ Make/maintain inventory of road infrastructure (roads, traffic signs, markings, ...)
- ✗ Provide all stakeholders with easy access to centralized data
- ✗ Enable offline and automated road quality control
- ✗ Save money thanks to predictive maintenance





# Why measuring roads? Automotive & Road Sector

## Safety

- ADAS functions such as lane keeping rely on clear road markings
- Worldwide yearly cost of bad roads is estimated to be: ??? (accidents, damaged vehicles, back injury, ...)
- Human, visual, on-site road inspection is slow and dangerous

## Maintenance planning

- Objective numbers reveal where and when to best spend road maintenance budget
- Road digitization documents evolution of road condition for road exploitation under consignment
- Acceptance of road (re)construction

## Comfort

- Delicate transport (e.g. non-urgent ambulance service) needs road quality for route selection
- SatNav feature: From A to B in most comfortable way
- Government aiming to increase of standard of living

## Self-driving cars

- Self-driving vehicles need road profile info for safe & comfortable navigation:
  - Pothole avoidance
  - Speed reduction at bumps
  - Curbstone detection
  - Platform localization for shuttles & buses

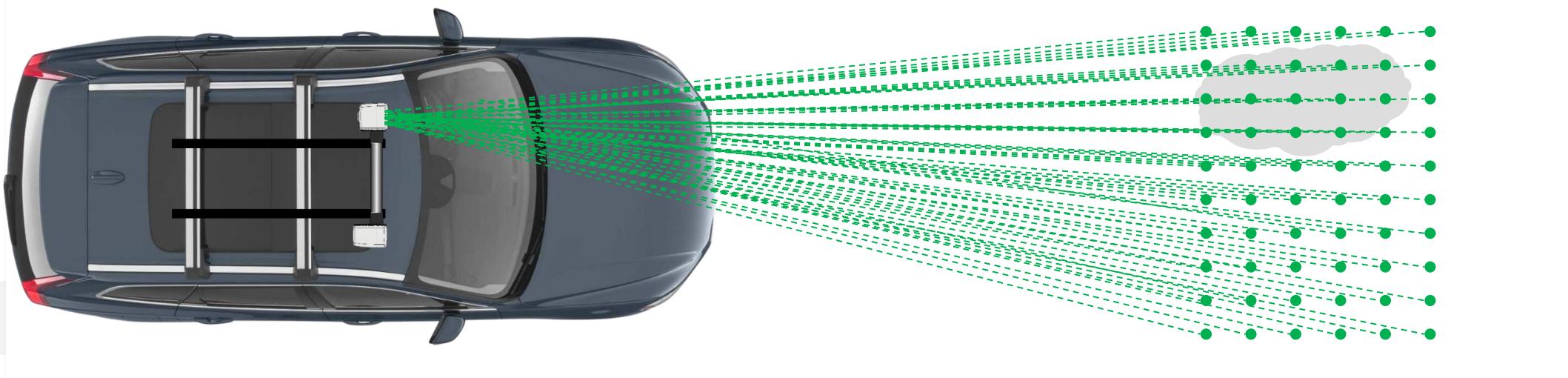
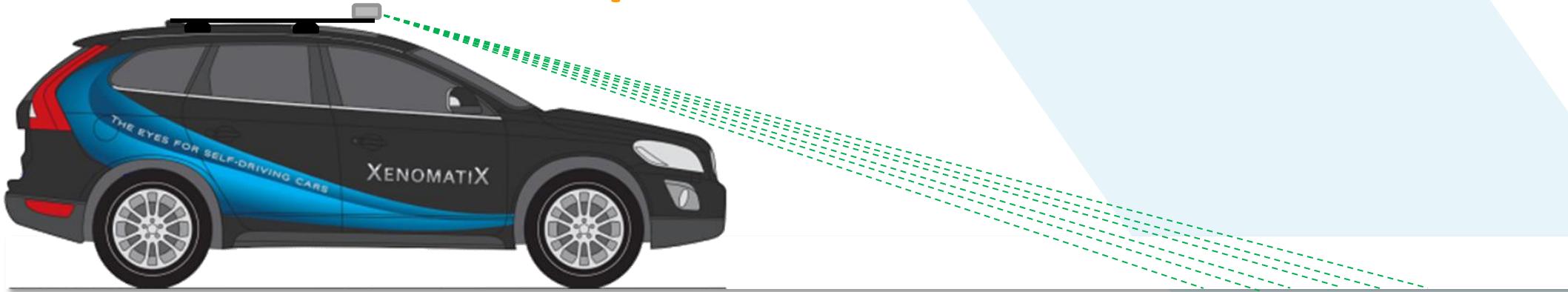


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# Measurement Principle





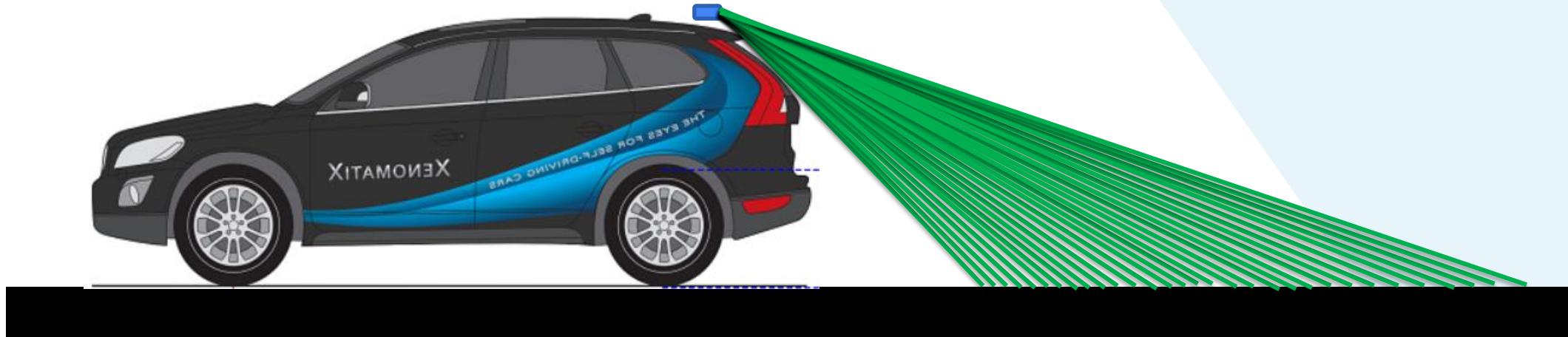
## Road digitization for Active Suspension



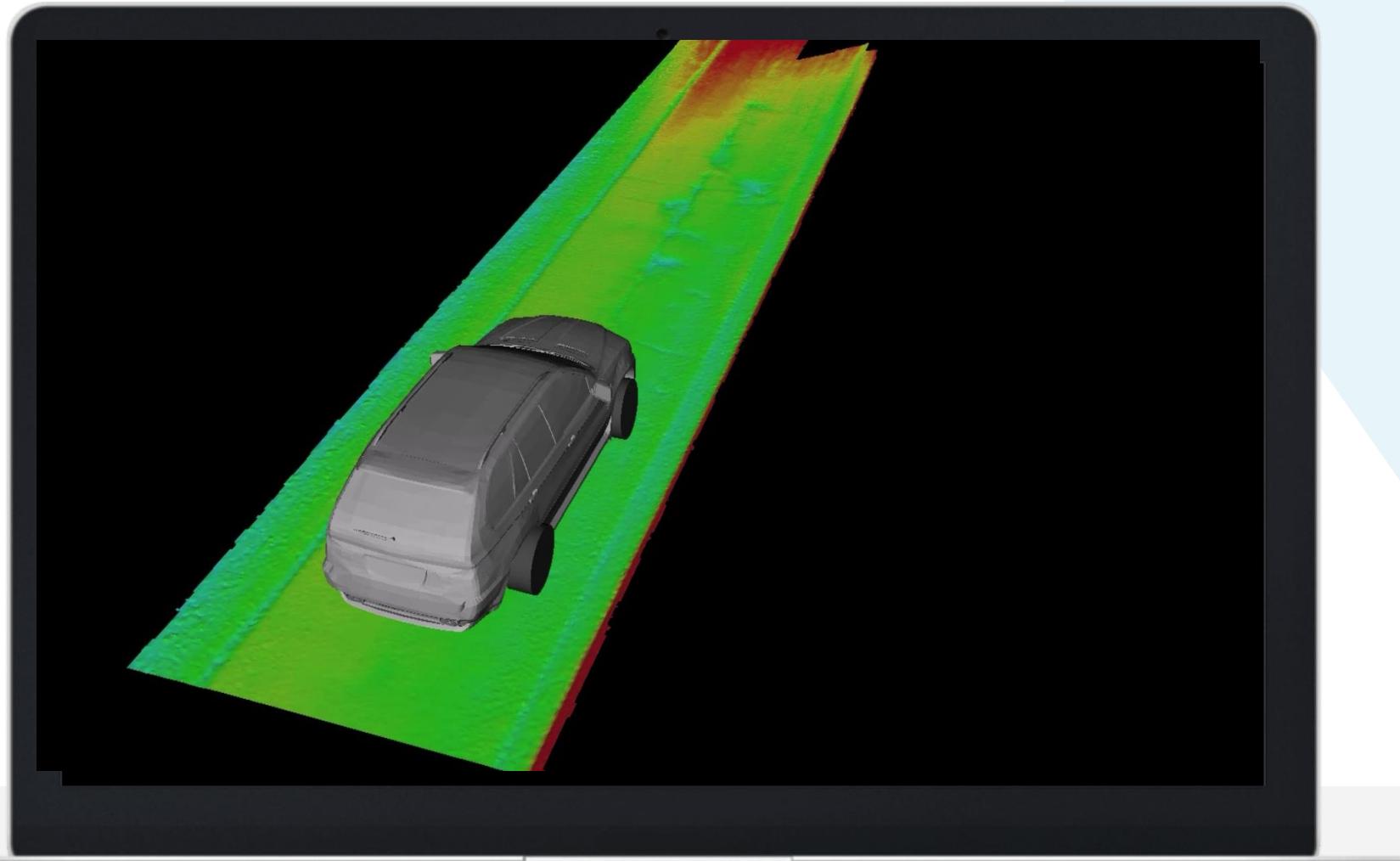


## How the Road LiDAR works

- ✗ Solid-state, multi-beam Lidar, developed for automotive applications
- ✗ High-accuracy short range Lidar for lane-wide measurements
- ✗ Independent from ambient light conditions
- ✗ Also used as road preview system for active suspension control



## Road damage

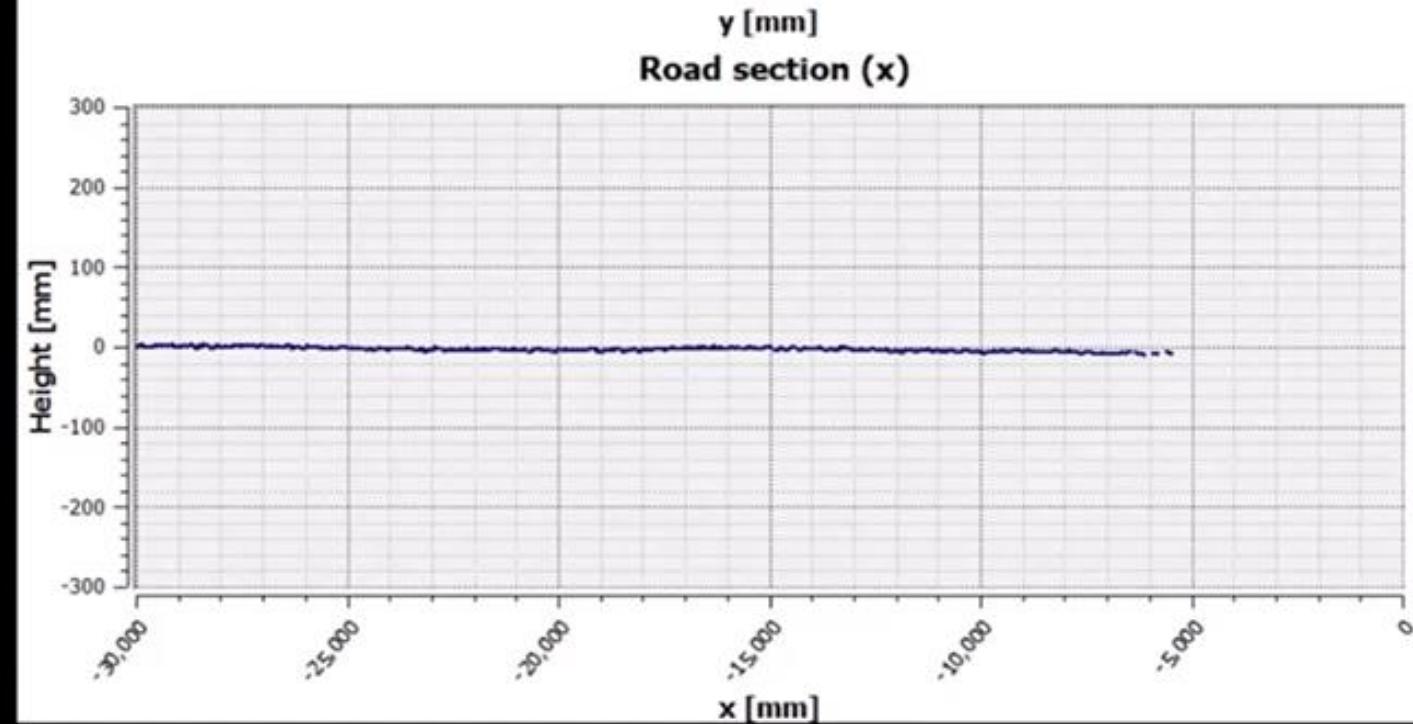
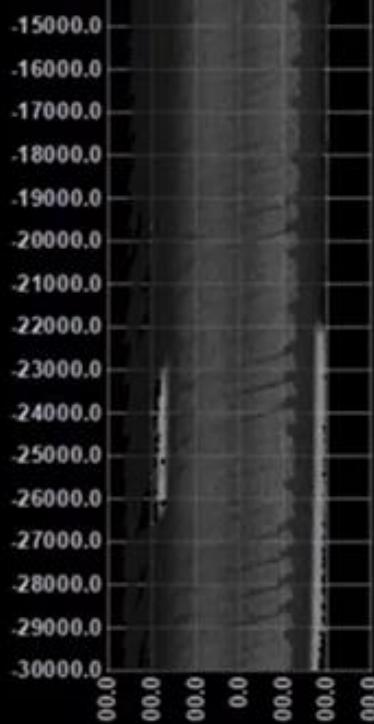


### 3D view reveals:

- ✗ Longitudinal and traversal cracks
- ✗ Potholes and repaired asphalt
- ✗ Gutter next to curbstone

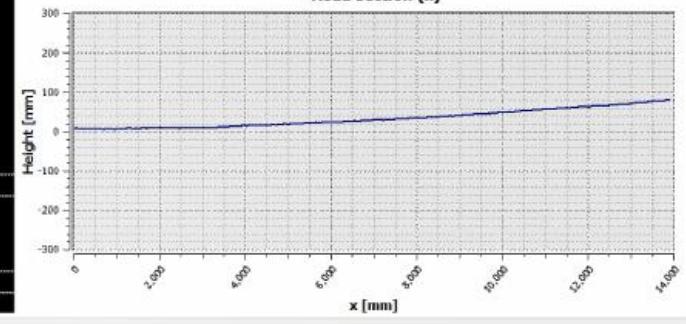
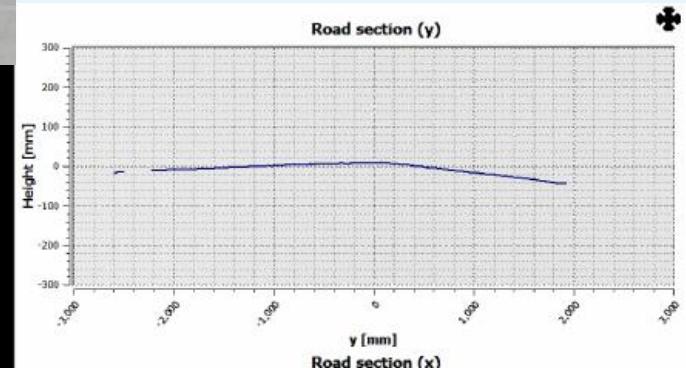
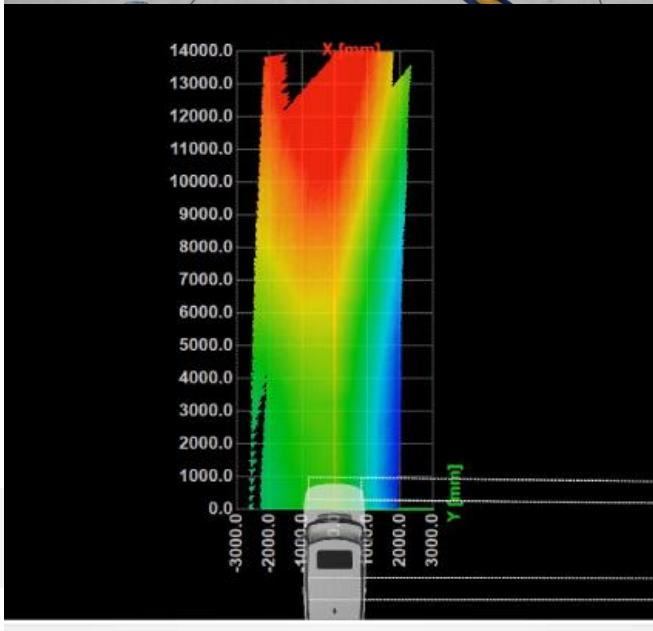


# Asphalt waviness inspection



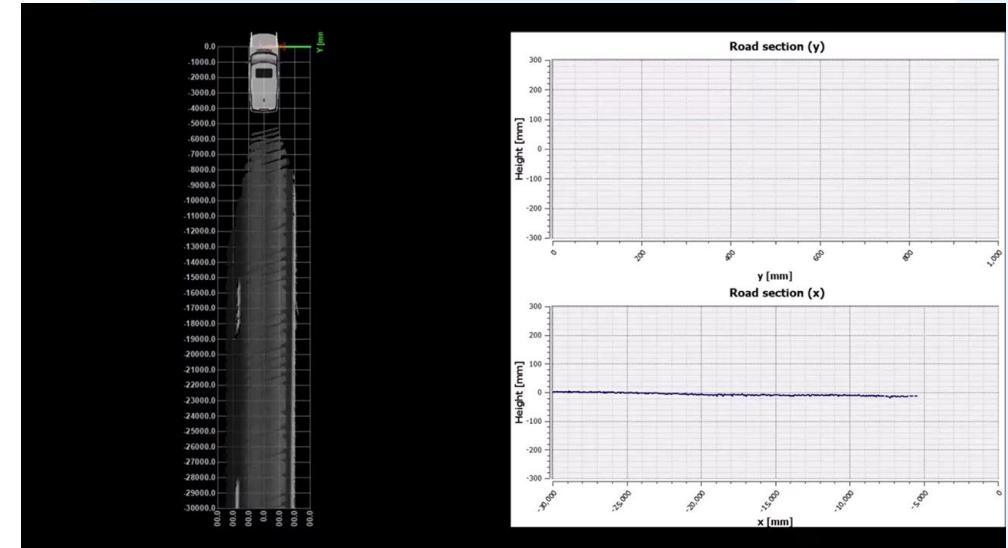


## Accuracy for airfield runways





# Automated Paving Equipment - milling, paving, compacting





## Value proposition of 6D road scanning





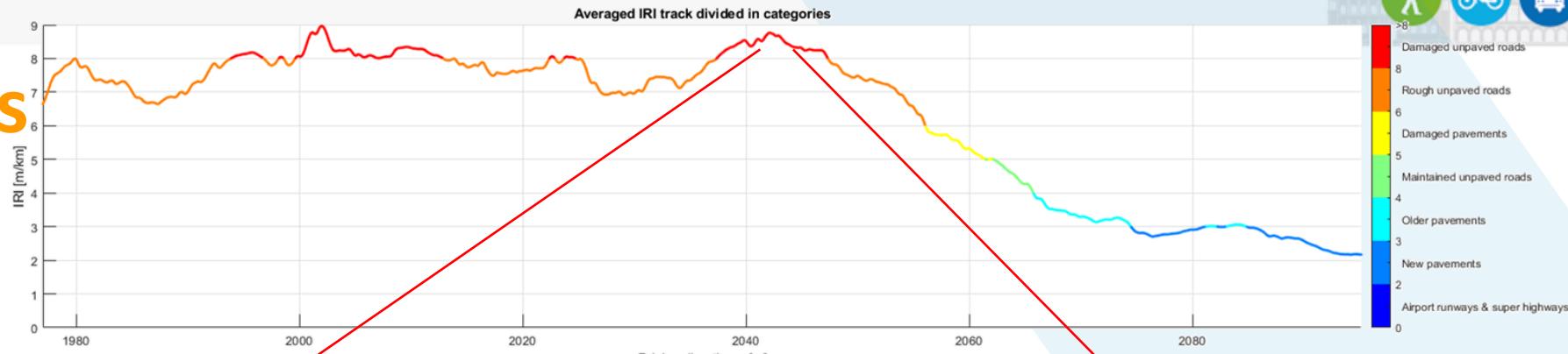
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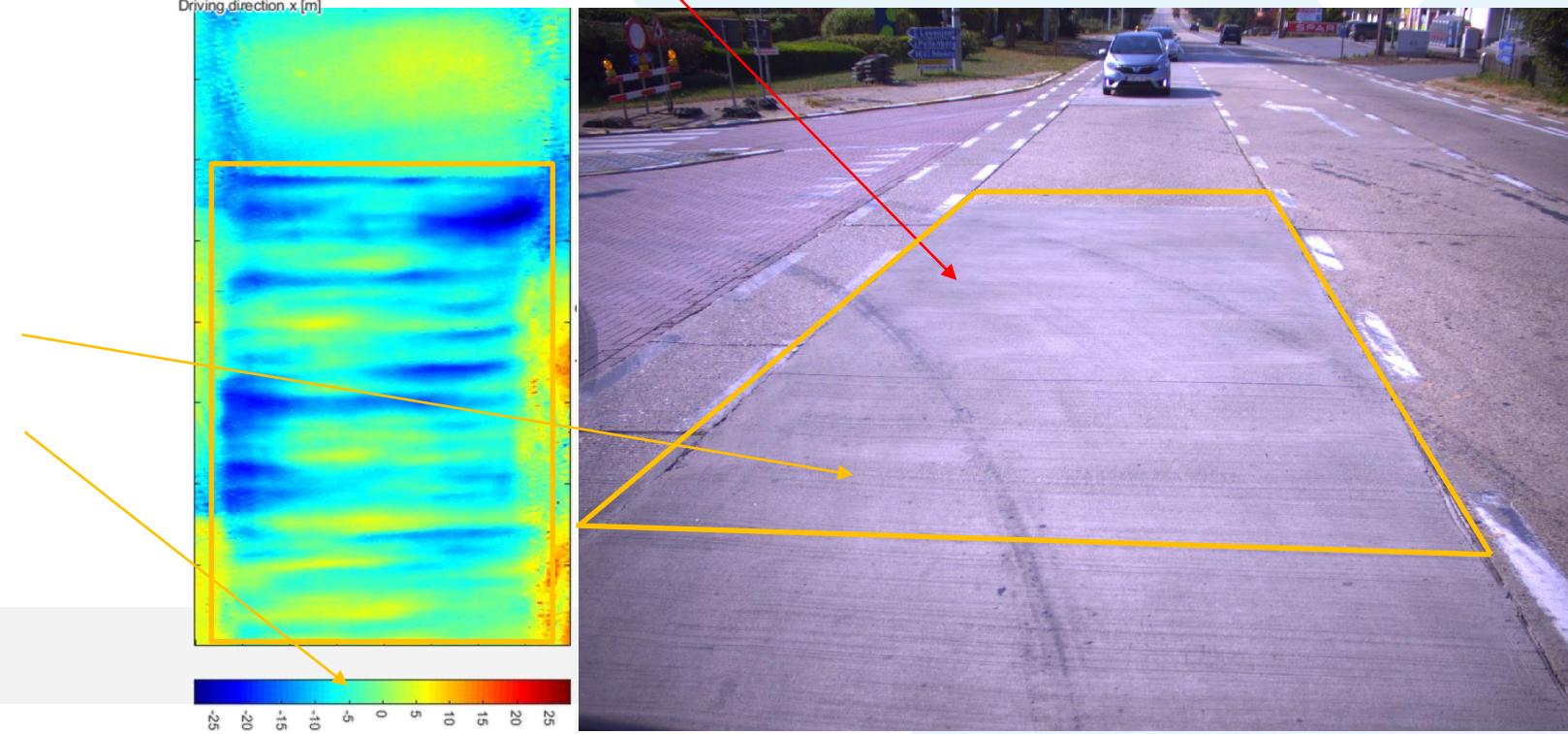




## IRI details



- Renewed road segment
- Distance = 2240 - 2283 m
- Poor quality due to grooves
- Conclusion: bad repair





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## Trend analysis

## Different layers of results

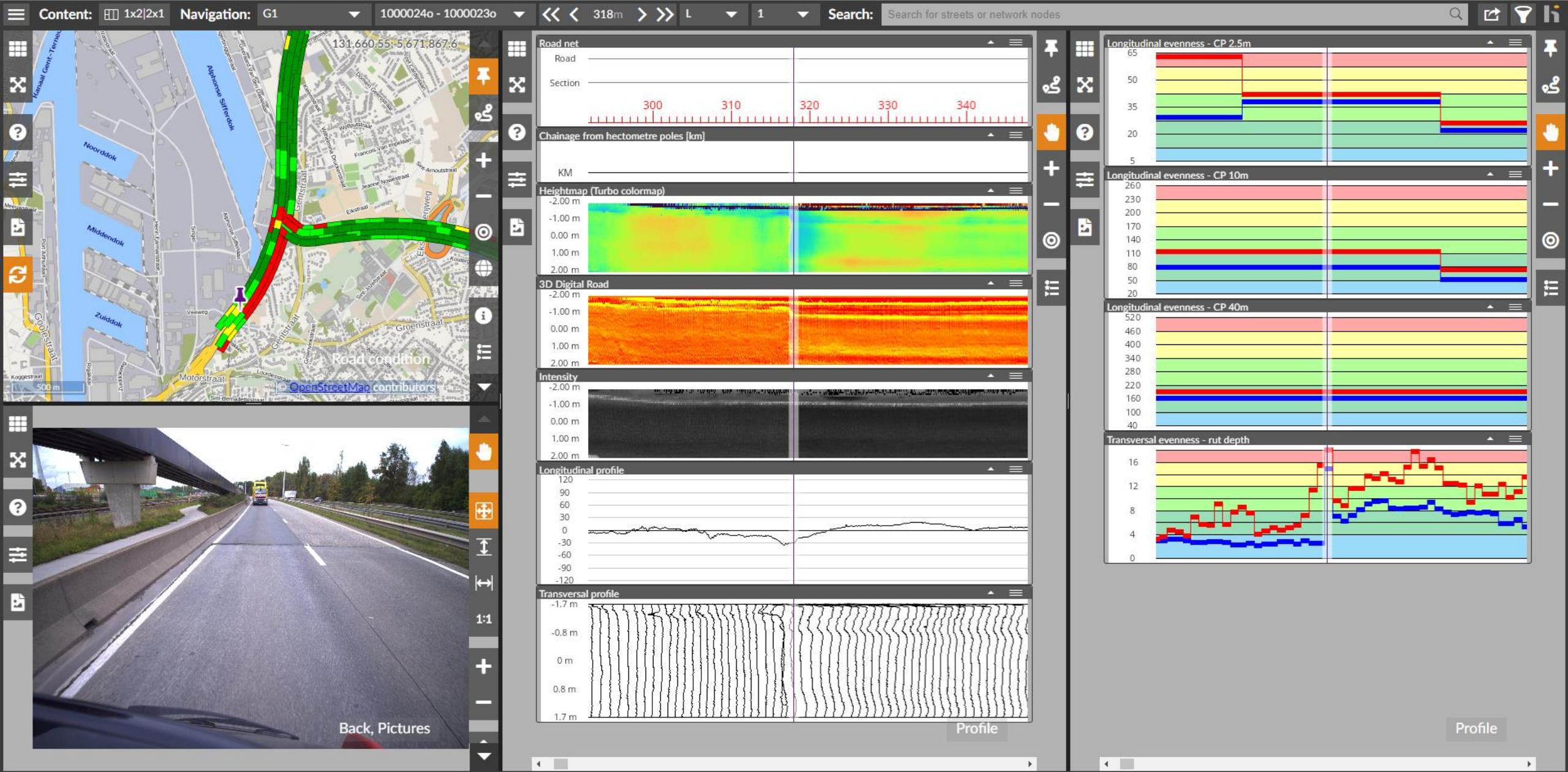
- Crack analysis
- Road degradation quantification
- Maintenance advices

## Road characteristics

- IRI
- Longitudinal waviness
- Transversal waviness / Rutting

## Realtime raw data

- 2D camera images every x meter
- **3D Digital Twin**
- Reflectivity map
- GPS & IMU value, synchronized with Lidar data





# Online Analysis – Comparison - Follow-up

The figure displays a software interface for road surveying and data analysis. It consists of several panels:

- Top Left:** Map of the road network in 2017, showing various road segments with labels like K 201, K 202, K 203, K 204, K 205, K 206, K 207, K 208, K 209, K 210, K 211, K 212, K 213, K 214, K 215, K 216, K 217, K 218, K 219, K 220, B 444, B 1, B 6, B 243, K 105, K 302, K 303, K 304, K 305, K 306, K 307, K 308, K 309, and A 7. The map is titled "Zustand (2017)".
- Top Right:** Camera image from a front-facing camera in 2017, showing a two-lane asphalt road with a grassy shoulder and a field in the background. The text "Frontkamera, ZEB 2017" is displayed below the image.
- Bottom Left:** Map of the road network in 2013, showing the same segments as the 2017 map but with different colors and line styles. The map is titled "Zustand (2013)".
- Bottom Right:** Camera image from a front-facing camera in 2013, showing the same road and field scene as the 2017 image. The text "Frontkamera, ZEB 2013" is displayed below the image.
- Right Side (2017 Data):**
  - Stationierung:** Shows stationing for station 38260180, with values 1000 and 1100. It includes labels for OD/FS, TP 1/3, and TE 2.
  - Längsebene 2017:** A longitudinal profile plot showing elevation (mm) from -200 to 200. The plot includes data for AUN, SBL, DBL, and LWI, with corresponding values in the table below.
  - Auswirkungen:** A table showing the impact of the 2017 profile on the road surface.
- Right Side (2013 Data):**
  - Stationierung:** Shows stationing for station 38260180, with values 1000 and 1100. It includes labels for OD/FS, TP 1/3, and TE 2.
  - Längsebene 2013:** A longitudinal profile plot showing elevation (mm) from -200 to 200. The plot includes data for AUN, SBL, DBL, and LWI, with corresponding values in the table below.
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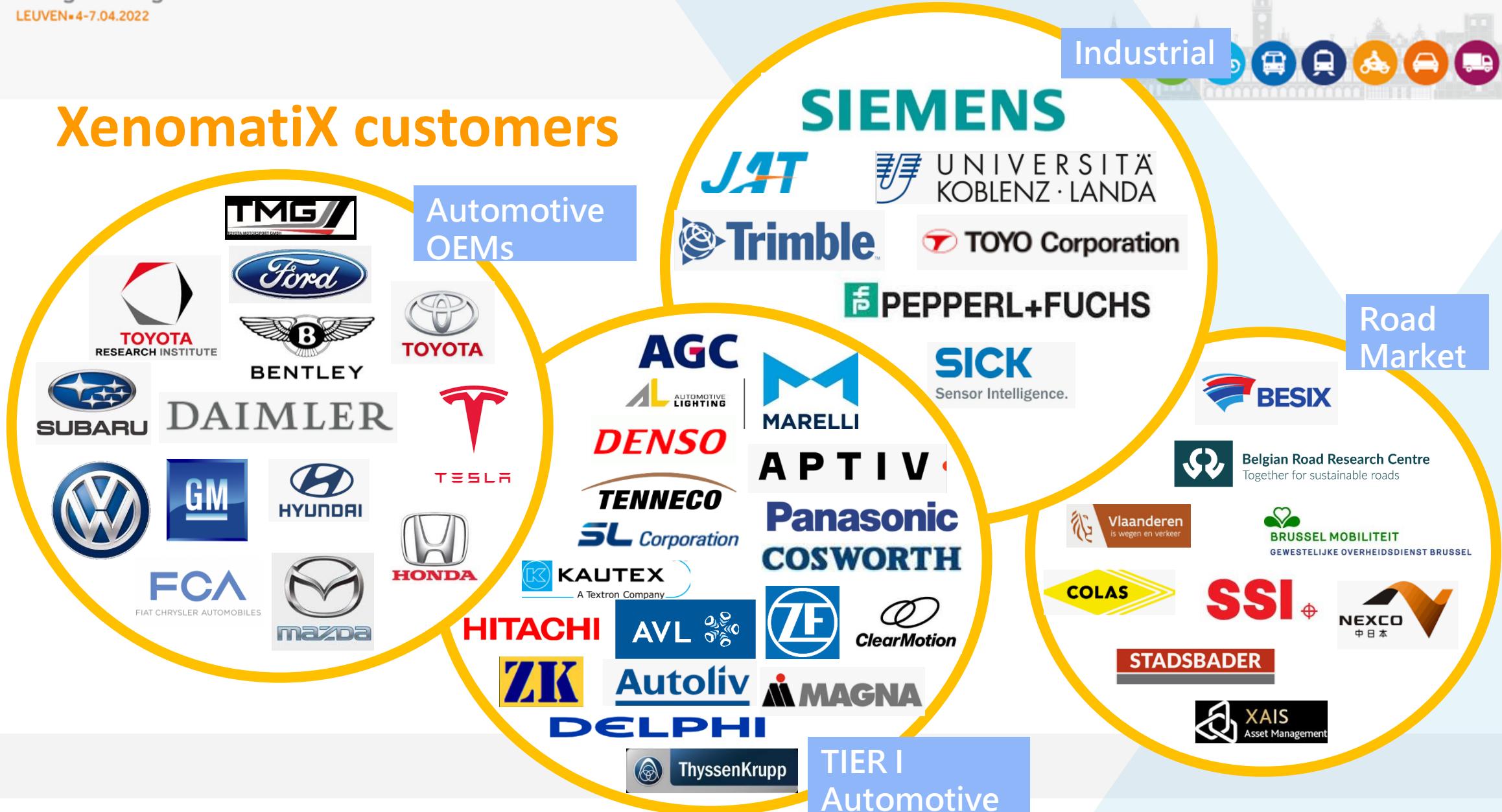
## What XenomatiX stands for

- ✗ XenomatiX provides **superior 3D sensing** for automotive applications.
- ✗ XenomatiX' novel LiDAR solutions enable reliable detection of road users, obstacles and road conditions for **safer and more comfortable driving**.





## XenomatiX customers





## Global representation

- ✗ Headquarters:  
**XenomatiX Belgium**
- ✗ Local offices:  
**XenomatiX Deutschland**  
**XenomatiX US**  
**XenomatiX China**
- ✗ Distribution channels for XenomatiX products:  
**Japan** through **TOYO CORPORATION**  
**US** through **TOYOTech**  
**South-Korea** through **JAT**  
**China** through **Shanghai ZK Auto Electronics**



## Awards From 2016 to 2022...





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## Take-aways

1. PMS requires regular pavement surveys
2. Automotive developments will increase survey frequency and will change our activities
3. It's not a threat but an opportunity
4. These technologies are available today for road surveying



## Contact XenomatiX



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